



# NPR College of Engineering & Technology

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# CS8501

# THEORY OF COMPUTATION

by,  
C.Kalpana,

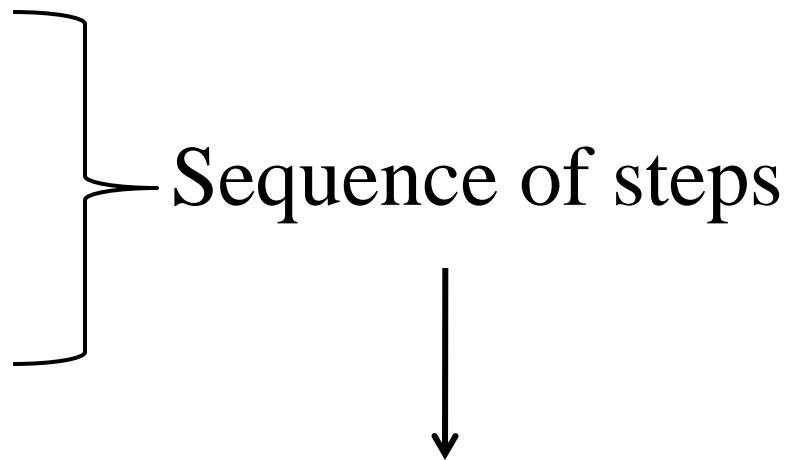
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Department of Computer Science and Engineering,  
NPR College of Engineering & Technology

# What is Computation?

# Why we need Computation?

- Calculation.
- To Solve a problem.
- To get a desired result.



Ex:- Algorithm

- Process of Computation





**What is to be computed?**

given problem

**How it should be Computed?**

via Calculative Steps

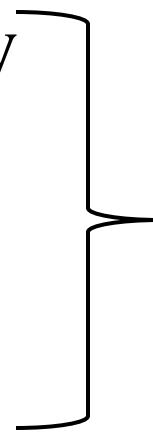
**Computability Theory**

**Automata Theory**

**How many steps does it take to perform?  
How much memory space is required?**

i.e., Time and Space Complexity

**Complexity Theory**

- Computability Theory
  - Automata Theory
  - Complexity Theory
- 
- Theory of Computation

# **Syllabus**

## **UNIT I AUTOMATA FUNDAMENTALS**

Introduction to formal proof – Additional forms of Proof – Inductive Proofs – Finite Automata – Deterministic Finite Automata – Non-deterministic Finite Automata – Finite Automata with Epsilon Transitions

# Definition of TOC

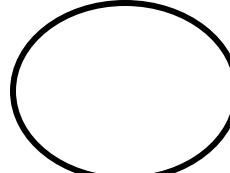
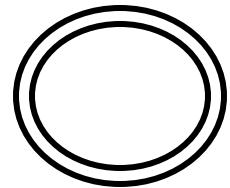
It is the branch that deals with “How efficiently the problems can be solved on a Model of computation using an Algorithm.”

# Definition of Automata

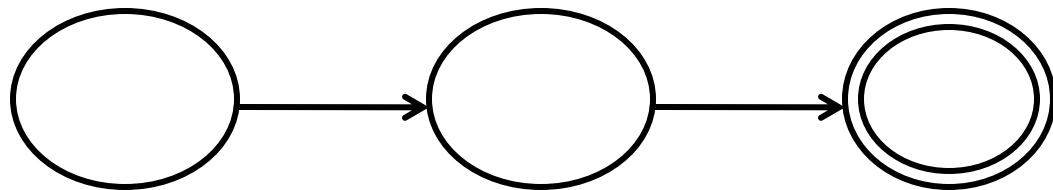
- Automaton or Automation
- Doing something by itself.
- It allows us to understand ‘How machines solve problems?

# Automata

- Set of states and Transitions.

- States - Circles 
- Transitions - Arrows 
- End of State - Double Circles 

# Automata



# Basic Terminologies

- Symbols
- Alphabet
- String
- Language

# Basic Terminologies

- **Symbols** – alphabet , letters

**Ex:-** a,b,c,0,1.....

- **Alphabet ( $\Sigma$ )** – Set of symbols, which are always finite.

**Ex:-**  $\Sigma = \{0,1....9\}$

$\Sigma = \{ a,b,c.... \}$

$\Sigma = \{ A,B,C.... \}$

# Basic Terminologies

- **Strings(w)** – Finite sequence of strings from some alphabet.

Length of string - $|w|$

- Number of symbols in the string.

**Ex:-** a,b,c,0,1.....

# Basic Terminologies

- **Language(L)** – collection of appropriate string.
- Finite or Infinite.
- **Finite**

Ex:-

$L_1 = \{ \text{ set of strings of length 2} \}$

**Answer:**  $L_1 = \{ aa, bb, 00, 11 \}$

- **Infinite**

Ex:-

$L_2 = \{ \text{ set of all strings starts with a } \}$

**Answer :**  $L_2 = \{ aa, ab, ac, aab, aac, abc. \dots \dots \}$

# Finite Automata (FA)

- Finite Automata consists of a finite set of states and a set of transitions from one state to another state.
- It occurs on input symbol chosen from an alphabet ( $\Sigma$ ).

# Language of Finite Automata

- 5 Tuples

$$M = ( Q, \Sigma, \delta, q_0, F )$$

Where ,

Q – Set of States.

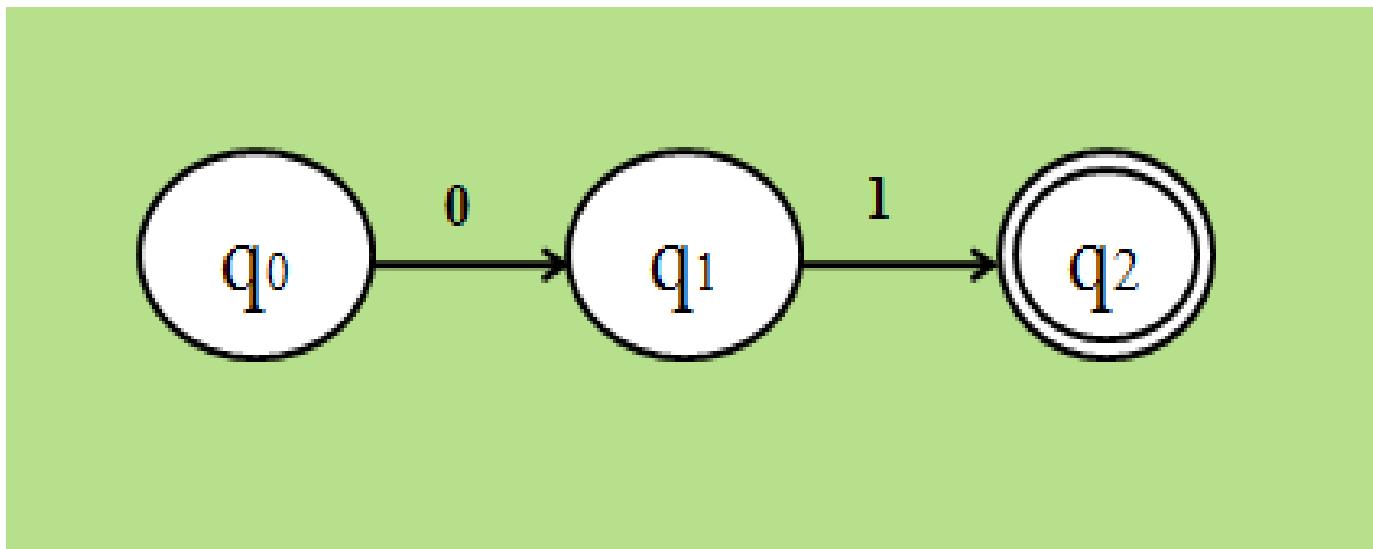
$\Sigma$  - Input alphabets

$\delta$  - Transition Function

$q_0$  - Start State

F- Final State

# Finite Automata



# **Finite Automata**

**Two Types**

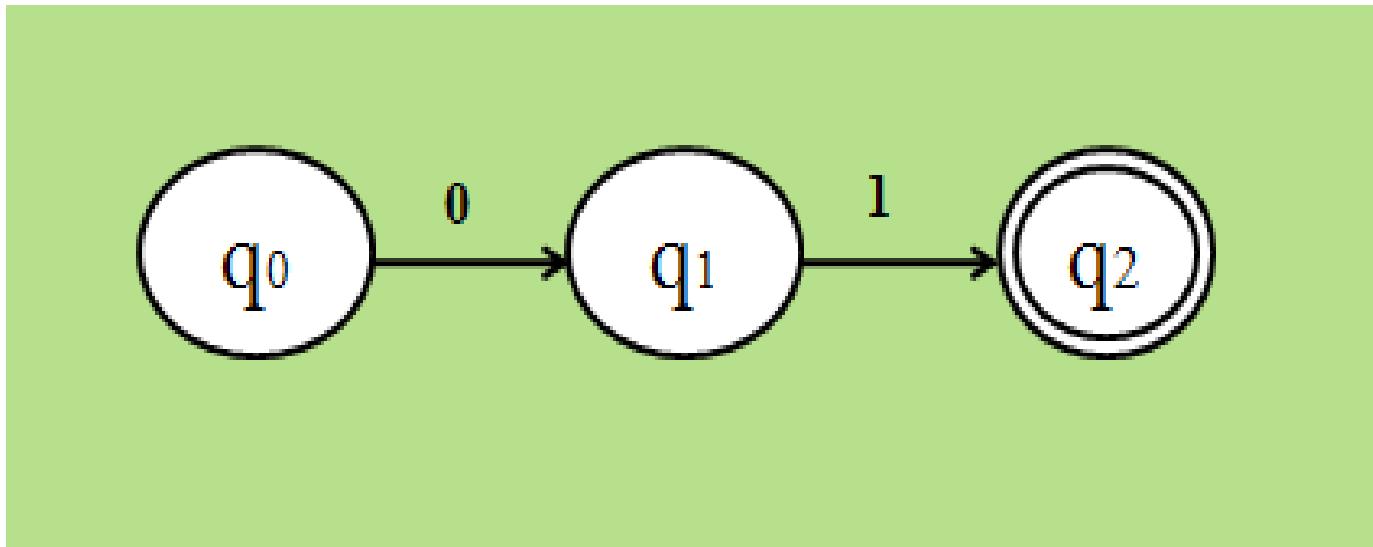
**1.DFA**

Deterministic Finite Automata

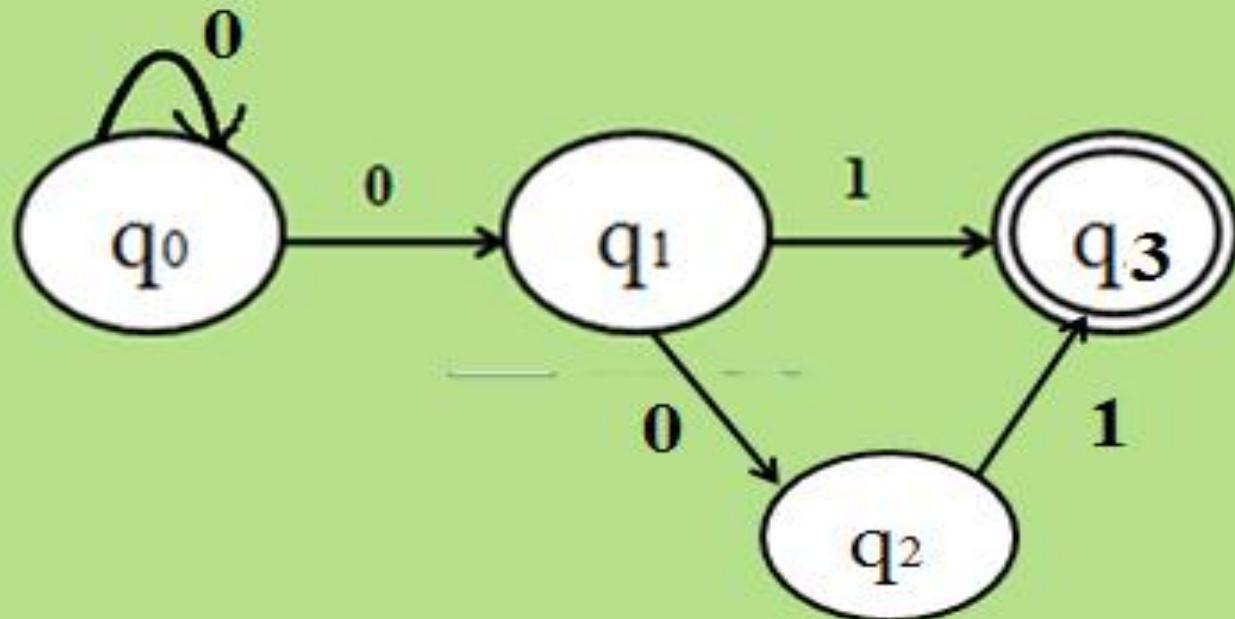
**2.NFA**

Non – Deterministic Finite Automata

# DFA



# NFA



# Basic Terminologies

- Symbols
- Alphabet
- String
- Language

# Basic Terminologies

- **Symbols** – alphabet , Numbers

**Ex:-** a,b,c,0,1.....

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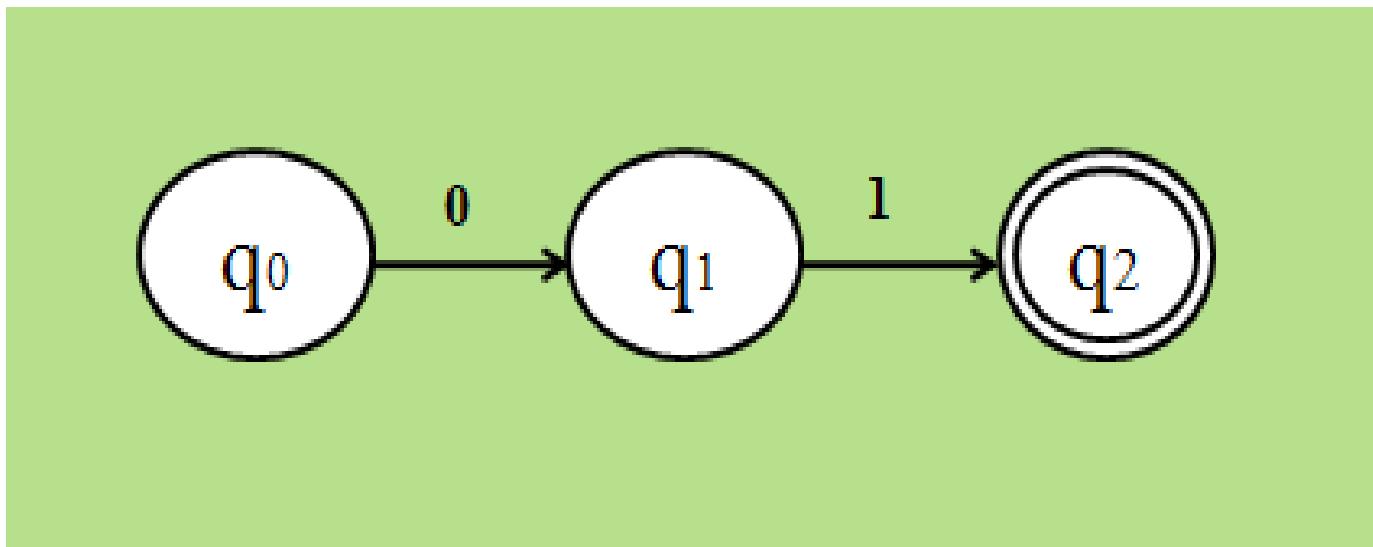
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# Finite Automata



# **Finite Automata**

**Two Types**

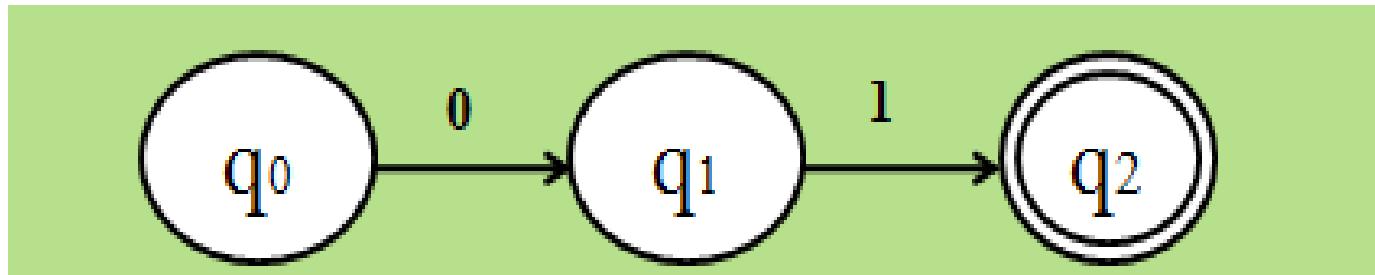
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Deterministic Finite Automata

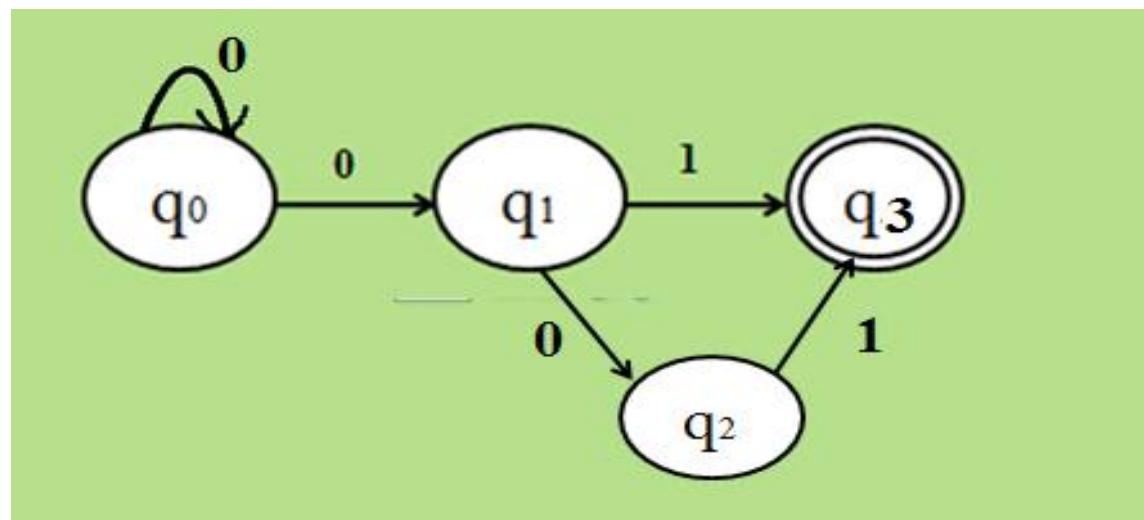
**2.NFA**

Non – Deterministic Finite Automata

# DFA



# NFA



# **Introduction to Formal Proofs**

## **Two Types**

**1.Deductive Proof**

**2.Inductive Proof**

# **Introduction to Formal Proofs**

## **1.Deductive Proof**

- Sequence of Statements given in logical order.
- To Prove Initial & Next Statement is True
- If H is True the C is also True
- H – Hypothesis
- C - Conclusion

# **Introduction to Formal Proofs**

## **2.Inductive Proof**

- Sequence of Parameterized Statements that uses the statement by itself.
- If A is True the B is also True
- A – Hypothesis
- B - Conclusion

# **Introduction to Formal Proofs**

## **1.Inductive Proof**

- Sequence of Parameterized Statements that uses the statement by itself.
- If A is True the B is also True
- A – Hypothesis
- B - Conclusion

# Three Steps in Inductive Proof

- Basis  $\rightarrow n = 0$  or  $1$
- Inductive Hypothesis  $\rightarrow n = k$
- Inductive Step  $\rightarrow n=k+1$

# Problem 1

1. Use mathematical induction to prove that

$$1 + 2 + 3 + \dots + n = n(n + 1) / 2 \text{ for all positive integers } n.$$

## Solution

- Let the statement  $P(n)$  be

$$1 + 2 + 3 + \dots + n = n(n + 1) / 2$$

- **STEP 1:** We first show that  $p(1)$  is true.
- **Left Side** = 1
- **Right Side** =  $1(1 + 1) / 2 = 1$
- Both sides of the statement are equal hence  $p(1)$  is true.

- **STEP 2:**
- We now assume that  $p(k)$  is true

$$1 + 2 + 3 + \dots + k = k(k + 1) / 2$$

and show that  $p(k + 1)$  is true

- **STEP 3**  $1 + 2 + 3 + \dots + k = k(k + 1) / 2$
- by adding  $k + 1$  to both sides of the above statement
- $1 + 2 + 3 + \dots + k + (k + 1) = k(k + 1) / 2 + (k + 1)$   
 $= (k + 1)(k / 2 + 1)$   
 $= (k + 1)(k + 2) / 2$

The last statement may be written as

$$1 + 2 + 3 + \dots + k + (k + 1) = (k + 1)(k + 2) / 2$$

Which is the statement  $p(k + 1)$ .

# **Additional Forms of Proofs**

- Proofs by Sets
- Proofs by Contradiction
- Proofs by Counter Example

# Finite Automata

- Finite Automata consists of set of states and transitions from one state to another state.
- It occurs from an input symbol chosen from alphabet  $\Sigma$ .

# Formal Definition of FA

or

## Language of FA

It has 5 Tuples

$$F = (Q, \Sigma, \delta, q_0, F)$$

Where,

$Q$  - Set of States

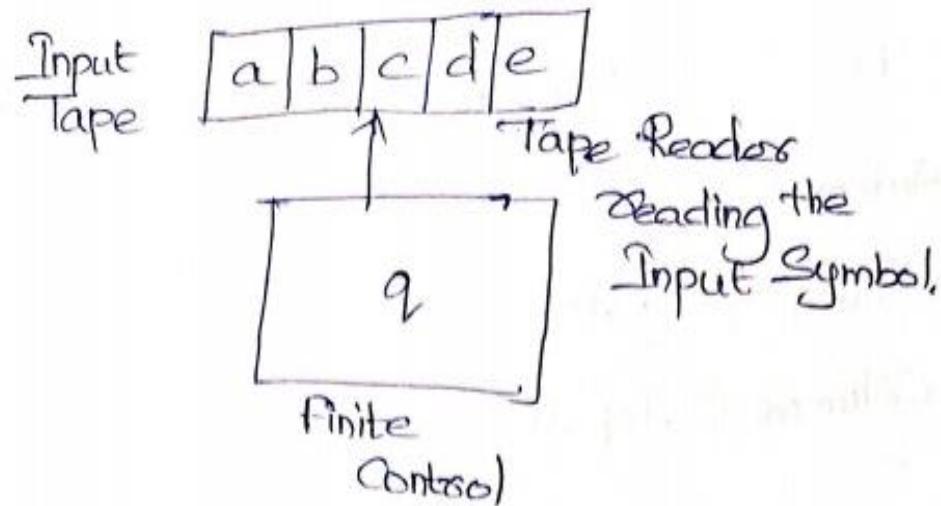
$\Sigma$  - Input Alphabets

$\delta$  - Transition function

$q_0$  - Starting State

$F$  - Final State.

# Finite Automata Model



Input Tape - Each Input is placed in the cell

Tape Reader - Read the Input Symbol from Left to Right

finite Control - Process the Input Symbol.

# Representation of FA

1. Transition Diagram
2. Transition Table

# Representation of FA

## 1. Transition Diagram

- Graph
- Finite set of states, Finite set of symbols and final

states

$q_0$   $\Rightarrow$  state

$\rightarrow q_0$   $\Rightarrow$  start state

$\circ$   $\Rightarrow$  End State

$\rightarrow \rightarrow$  Transitions from one state to another.

# **Representation of FA**

## **2. Transition Table**

- Tabular representation
- Rows – States & Columns - Inputs

# Types of Finite Automata

1. Deterministic Finite Automata (DFA)
2. Non-Deterministic Finite Automata(NFA)

# **DFA**

- In DFA, for each input symbol, one can determine the state to which the machine will move.
- **Deterministic Finite Machine** (or)
- **Deterministic Finite Automaton.**

# Formal Definition of DFA

$$M = (\mathcal{Q}, \Sigma, \delta, q_0, F)$$

Where,

$\mathcal{Q}$  - Set of States

$\Sigma$  - Input Symbols

$\delta$  - Transition function

$q_0$  - Start State

$F$  - final State

# Operations of DFA

- Initial State
- Input Process
- For each move, it accepts only one input symbol.
- If the input reaches the final state, then the given input will be accepted or rejected

# Transition Function

TRANSITION FUNCTION

$$\delta(q, wa) = \delta(\delta(q, a), w)$$

Where       $w$  = Given String

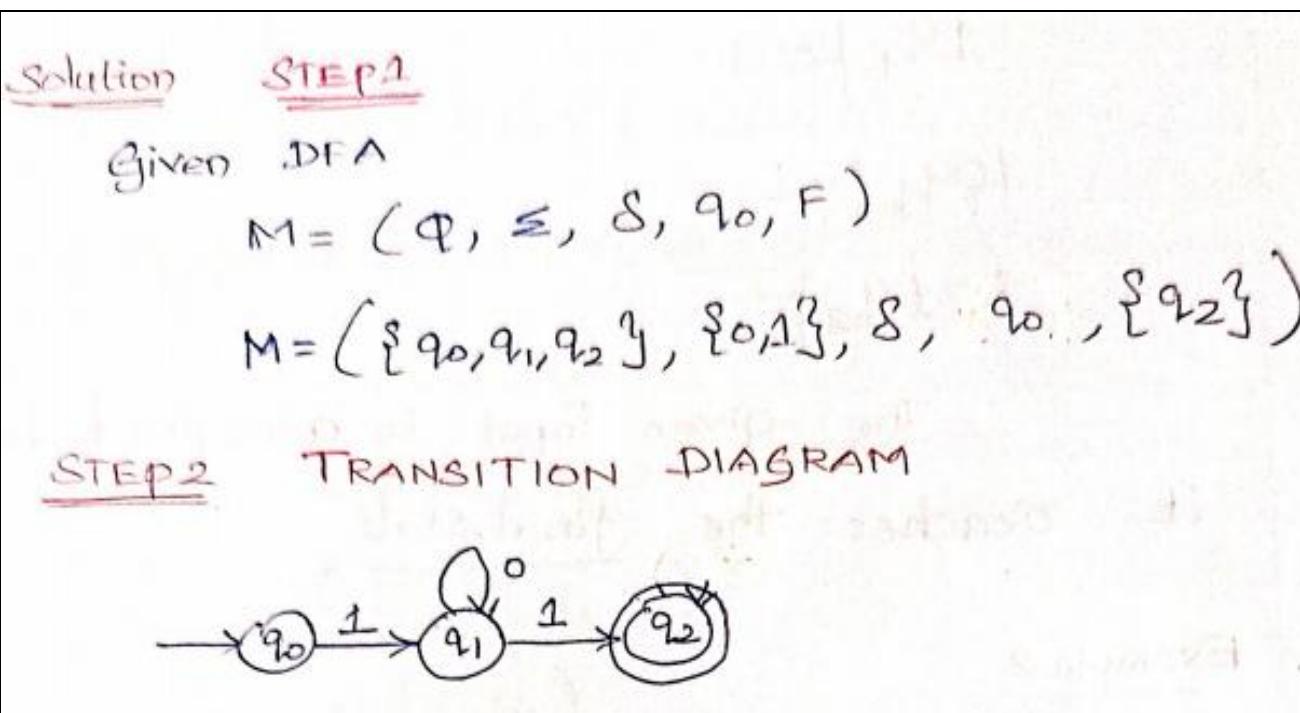
$a$  - first Input Symbol.

## **DFA Example**

**1. Design a DFA that accepts only the input 10 over the set {0,1}.**

# DFA Example

2. Design a DFA that accepts only the input 101 over the set {0,1}.



### STEP 3 TRANSITION TAB

STATE	0	1
$\rightarrow q_0$	$\phi$	$\{q_1\}$
$q_1$	$\{q_1\}$	$\{q_2\}$
$*q_2$	$\phi$	$\phi$

### STEP 4 TRANSITION FUNCTION

$$\delta(q, \omega a) \Rightarrow \delta(q, \omega a) = \delta(\delta(q, a), \omega)$$

$\omega = 101$  (Given string)

$$= \delta(\delta(q_{\underline{0}}, 1), 01)$$

$$= \delta(\delta(q_1), 01)$$

$$= \delta(\delta(q_1, 0), 1)$$

$$= \delta(\delta(q_1), 1)$$

$$= \delta(\delta(q_1, 1)) \Rightarrow \delta(q_2) \Rightarrow q_2 // \text{Accepted}$$

## METHOD 2 TRANSITION FUNCTION

First write the starting state.

$$q_0 \vdash 101$$

$$1q_1 \vdash 01$$

$$10q_1 \vdash 1$$

$$101q_2 \vdash$$

∴ The given input is accepted because  
it reaches the final state.

# Equivalence of DFA & NFA

## EXAMPLE PROBLEMS.

1. Construct DFA equivalent to the NFA

$$M = (\{P, q, \sigma\}, \{0, 1\}, \delta, P, \{q, s\})$$

Where  $\delta$  is defined in the following table.

$\delta$	0	1
P	$\{q, s\}$	$\{q\}$
q	$\{\sigma\}$	$\{q, \sigma\}$
$\sigma$	$\{s\}$	$\{P\}$
s	—	$\{P\}$

Solution

STEP1

Let  $M = (Q, \leq, \delta, q_0, F)$

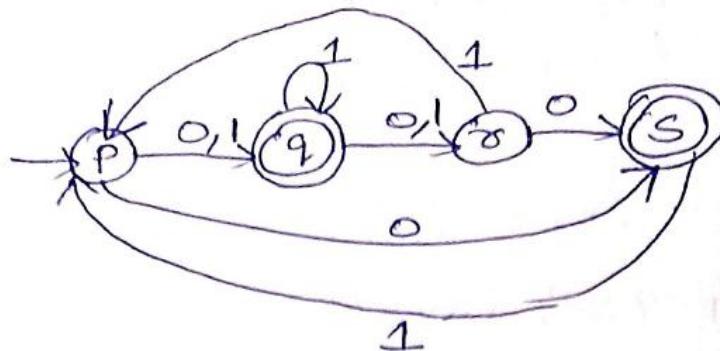
$M = (\{P, q, s\}, \{0, 1\}, \delta, P, \{q, s\})$

Starting State = P

Final State = {q, s}

STEP2

TRANSITION DIAGRAM



STEP 3

Construct Subsets

$$\boxed{\text{Formula} = 2^n}$$

$n = \text{Total number of States} = 4$

$$2^n = 2^4 = 2 \times 2 \times 2 \times 2 = 16 \text{ States}$$

$$\Phi = \left( \{ \emptyset, \{P\}, \{q\}, \{\sigma\}, \{s\}, \{P, q\}, \{P, \sigma\}, \{P, s\}, \{\sigma, s\}, \{q, \sigma\}, \{q, s\}, \{P, q, \sigma\}, \{P, q, s\}, \{P, \sigma, s\}, \{q, \sigma, s\}, \{P, q, \sigma, s\} \right)$$

STEP 4 Transition function for Subset Construction.

$\delta$	0	1
$\phi$	$, \phi$	$\phi$
$\rightarrow P$	$\{q, s\}$	$\{q\}$
* (q)	$\{\gamma\}$	$\{q, \gamma\}$
$\gamma$	$\{s\}$	$\{P\}$
* (S)	-	$\{P\}$
+ (P, q)	$\{q, s, \gamma\}$	$\{q, \gamma\}$
$\{P, \gamma\}$	$\{q, s\}$	$\{P, q\}$

	O	I
*	{P, S}	{Q, S}
*	{Q, R}	{P, Q, R}
*	{Q, S}	{P, Q, R}
*	{R, S}	{P}
*	{P, Q, R}	{Q, S, R}
*	{P, Q, S}	{P, Q, R}
*	{P, R, S}	{P, Q}
*	{Q, R, S}	{P, Q, R}
*	{P, Q, R, S}	{P, Q, R}

$\delta$	O	I
$\phi$	$\phi$	$\phi$
$\rightarrow P$	{Q, S}	{Q}
* (Q)	{R}	{Q, R}
R	{S}	{P}
* (S)	-	{P}

$\delta$	0	1
$\phi$	$\phi$	$\phi$
$\rightarrow P$	$\{q, s\}$	$\{q\}$
* (q)	$\{\bar{q}\}$	$\{q, \bar{q}\}$
$\bar{q}$	$\{s\}$	$\{P\}$
* (S)	-	$\{P\}$

STEP 5 To Construct DFA,

find transition function.

Here, the states will get minimized.

Start with starting state.

i)  $\delta(P, 0) = \{q, s\} \rightarrow$  New state generated.

Note  $\Rightarrow$  [See the question it has only 4 states  $(P, q, \bar{q}, s)$ . Here  $\{q, s\}$  is new state],

ii)  $\delta(P, 1) = \{q\}$

iii)  $\delta(q, 0) = \{\bar{q}\}$

iv)  $\delta(q, 1) = \{q, \bar{q}\} -$  New state

v)  $\delta(\bar{q}, 0) = \{s\}$

vi)  $\delta(\bar{q}, 1) = \{P\}$

vii)  $\delta(s, 0) = - \oplus \phi$

viii)  $\delta(s, 1) = \{P\}$

Find transitions for New state.

$$ix) \delta(\{q,s\}, 0) = \{\sigma\}$$

New states

$$x) \delta(\{q,s\}, 1) = \{P, q, \sigma\} - \text{New State}$$

$\{q, s\}, \{q, \sigma\}$   
till now.

$$xi) \delta(\{q, \sigma\}, 0) = \{\sigma, s\} - \text{New state}$$

$$xii) \delta(\{q, \sigma\}, 1) = \{P, q, \sigma\} - \text{New state}$$

$$xiii) \delta(\{P, q, \sigma\}, 0) = \{q, \sigma, s\} - \text{New state}$$

$$xiv) \delta(\{P, q, \sigma\}, 1) = \{P, q, \sigma\}$$

$$xv) \delta(\{\sigma, s\}, 0) = \{s\}$$

$$xvi) \delta(\{\sigma, s\}, 1) = \{P\}$$

$$xvii) \delta(\{q, \sigma, s\}, 0) = \{\sigma, s\}$$

$$xviii) \delta(\{q, \sigma, s\}, 1) = \{P, q, \sigma\}$$

$\therefore$  We find transition function for all the  
New states.

Next Step  $\Rightarrow$  Draw transition table.

$\delta$	0	1
$\phi$	$\phi$	$\phi$
$\rightarrow P$	$\{q, s\}$	$\{q\}$
* (q)	$\{\sigma\}$	$\{q, \sigma\}$
$\sigma$	$\{s\}$	$\{P\}$
* (s)	-	$\{P\}$

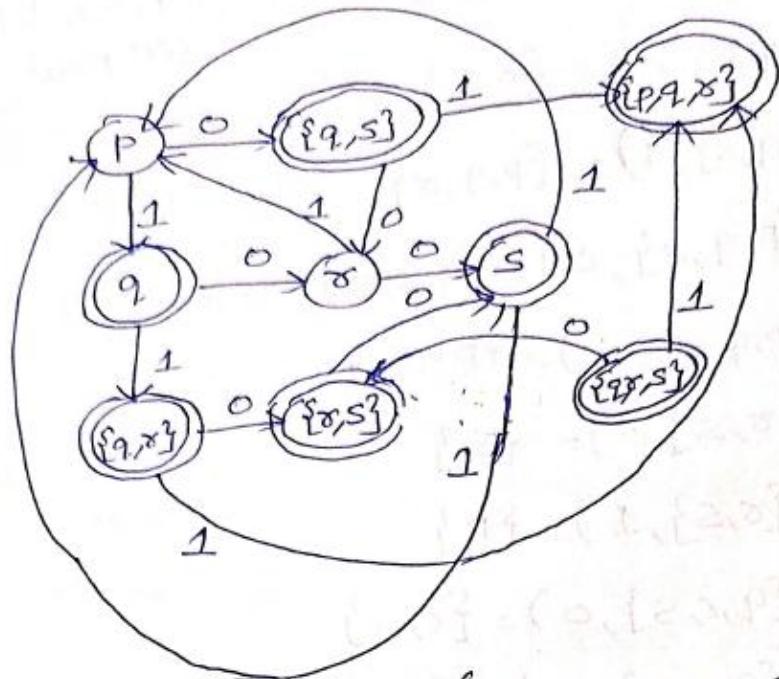
STEP 6

## DFA TRANSITION TABLE

$\delta$	0	1
$\rightarrow P$	$\{q, s\}$	$\{q\}$
*	(q)	$\{\bar{x}\}$
x	$\{s\}$	$\{p\}$
*	(S)	-
*	$\{q, s\}$	$\{\bar{x}\}$
*	$\{q, \bar{x}\}$	$\{s, \bar{x}\}$
*	$\{p, q, \bar{x}\}$	$\{q, \bar{x}, s\}$

$\delta$	0	1
*	$\{\bar{x}, s\}$	$\{s\}$
*	$\{q, \bar{x}, s\}$	$\{\bar{x}, s\}$

STEP 7 DFA TRANSITION DIAGRAM



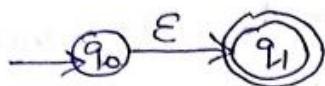
∴ Final States are  $(\{q\}, \{s\}, \{q, \tau\}, \{q, s\}, \{\tau, s\}, \{q, \tau, s\}, \{q, \tau, s\}, \{P, q, \tau, s\})$ .

## FINITE AUTOMATA WITH EPSILON TRANSITIONS

[E - Epsilon]

- \* The E-transition in NFA, which helps to move from one state to another state without having an input symbol from the set  $\Sigma$ .

Ex:



- \* Here, the E (epsilon) moves from the state  $q_0$  to  $q_1$ .
- \* In E-NFA, we can simply change the states from one state to another.

## DEFINITION OF NFA with $\epsilon$

\* The language L accepted by NFA with  $\epsilon$ , denoted by  $M = (\Phi, \Sigma, \delta, q_0, F)$  can be defined as,

Let  $M = (\Phi, \Sigma, \delta, q_0, F)$  be a NFA with  $\epsilon$ .

Where,

$\Phi$  - Finite Set of States.

$\Sigma$  - Input Symbols

$\delta$  - Transition function

$\boxed{\Phi \times \{\Sigma \cup \epsilon\} \text{ to } 2^\Phi}$

$q_0$  - Start State

F - final State

It has 5 steps,

1. Formal Notation
  2. Epsilon closures
  3. Extended Transition for epsilon ( $\epsilon$ -NFA).
  4. Eliminating  $\epsilon$ -Transition.
  5. Language of  $\epsilon$ -NFA.
1. FORMAL NOTATION:

Let  $\epsilon$ -NFA can be represented as,

$$M = (\Phi, \Sigma, \delta, q_0, F)$$

Where  $\delta$  has the arguments,

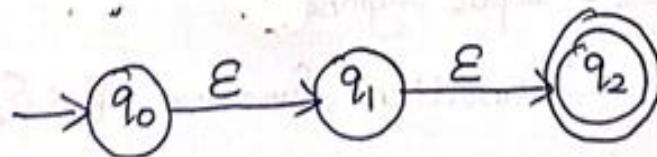
- i) A state in  $\Phi$
- ii) A New Input Symbol  $\underline{\epsilon}$  is added to the set  $\Sigma$ .

## 2. EPSILON CLOSURE ( $\epsilon$ -CLOSURE)

\* Epsilon ( $\epsilon$ ) means present state can go to other state without any input.

\* Epsilon closure is finding all the states which can be reached from the present state on one or more epsilon transitions.

Ex:



$$\epsilon\text{-closure}(q_0) = \{q_0, q_1, q_2\}$$

$$\epsilon\text{-closure}(q_1) = \{q_1, q_2\} \quad \xrightarrow{\epsilon\text{-moves}}$$

$$\epsilon\text{-closure}(q_2) = \{q_2\}$$

### 3. EXTENDED TRANSITION FUNCTION for $\epsilon$ -NFA.

Let  $E = (Q, \Sigma, \delta, q_0, F)$  be the  $\epsilon$ -NFA,

then  $\hat{\delta}$  is the extended transition function.

\* The extended transition function  $\hat{\delta}$  is

defined as,

$$i) \hat{\delta}(q, \omega) = \epsilon\text{-closure}(q)$$

ii) for  $\omega \in \Sigma^*$  and  $a \in \Sigma$ ,

$$\hat{\delta}(q, \omega a) = \epsilon\text{-closure}(P)$$

Where,

$$P = \{ p \mid \begin{array}{l} \text{for some } \sigma \text{ in } \hat{\delta}(q, \omega), \\ p \text{ is in } \delta(\sigma, a) \end{array} \}$$

$$iii) \delta(R, a) = \bigcup_{q \in R} \delta(q, a)$$

$$iv) \delta(R, \omega) = \bigcup_{q \in R} \hat{\delta}(q, \omega).$$

#### 4. ELIMINATING $\epsilon$ -TRANSITIONS.

\* It is possible to construct DFA D that accepts the same language as  $\epsilon$ -NFA.

Let  $E = (\Phi_E, \Sigma, S_E, q_0, F_E)$ .

\* Then the equivalent DFA  $D = (\Phi_D, \Sigma, S_D, q_0, F_D)$  is constructed as follows.

1.  $\Phi_D$  is the subset of  $\Phi_E$ .
2.  $q_0 = \epsilon\text{-closure}(q_0)$  is the start state of D.
3.  $F_D$  is the final state that contain atleast one accepting state of E.

i.e.,  $F_D = \{S \mid S \text{ in } Q_D \text{ and } S \cap F \neq \emptyset\}$

4.  $\delta_D(S, a)$  is computed by,

i) Let  $S = \{P_1, P_2, \dots, P_k\}$

ii) Compute  $\bigcup_{i=1}^k \delta(P_i, a) = \{\alpha_1, \alpha_2, \dots, \alpha_m\}$

iii)  $\delta_D(S, a) = \bigcup_{j=1}^M \epsilon\text{-closure}(\alpha_j)$

### 5. LANGUAGE OF $\epsilon$ -NFA.

\* The language of an  $\epsilon$ -NFA is

$E = (\Phi, \leq, \delta, q_0, F)$  is

$L(E) = \{w \mid \delta(q_0, w) \cap F \neq \emptyset\}$

i.e., the language of  $E$  is the set of strings  $w$  that take the start state to atleast one accepting state.

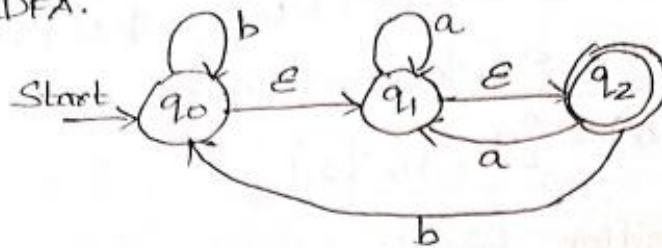
## CONVERSION OF NFA with $\epsilon$ to DFA.

### PROBLEM STEPS.

1. find  $\epsilon$ -closure.
2. find Transition function from  $\epsilon$ -closure of Start State.
3. find Transition function for each and every New State.
4. Draw Transition  $\xrightarrow{\text{Table}}$  Diagram for DFA.
5. Write the final states.  
(Mention).

EXAMPLE PROBLEMS

1. Convert the following NFA with  $\epsilon$  to equivalent DFA.



Solution

STEP 1 Find  $\epsilon$ -closures.

$$\epsilon\text{-closure } \{q_0\} = \{q_0, q_1, q_2\}$$

$$\epsilon\text{-closure } \{q_1\} = \{q_1, q_2\}$$

$$\epsilon\text{-closure } \{q_2\} = \{q_2\}$$

STEP 2

Let us start from  $\epsilon$ -closure of start state

$$\epsilon\text{-closure } \{q_0\} = \{q_0, q_1, q_2\} - \text{New state}$$

Step 3

Find Transitions for New State to Input a, b

$$i) \delta(\{q_0, q_1, q_2\}, a) = \underline{\underline{\text{E-closure}}}(\delta(\{q_0, q_1, q_2\}, a))$$

Refer diagram

$$= \text{E-closure}(\delta(q_0, a) \cup \delta(q_1, a) \cup \delta(q_2, a))$$

$$= \text{E-closure}(\emptyset \cup \{q_1\} \cup \{q_1\})$$

$$= \text{E-closure}(\{q_1\})$$

$$\boxed{\delta(\{q_0, q_1, q_2\}, a) = \{q_1, q_2\}}$$

- New State

$\epsilon$ -closure  $\{\underline{q_0}\} = \{q_0, q_1, q_2\}$

$\epsilon$ -closure  $\{q_1\} = \{q_1, q_2\}$

$\epsilon$ -closure  $\{q_2\} = \{q_2\}$

ii)  $\delta(\{q_0, q_1, q_2\}, b) = \epsilon\text{-closure}(\{q_0, q_1, q_2\}, b)$

$$\begin{aligned}&= \epsilon\text{-closure}(\{q_0, b\} \cup \{q_1, b\} \cup \{q_2, b\}) \\&= \epsilon\text{-closure}(\{q_0\} \cup \emptyset \cup \{q_0\}) \\&= \epsilon\text{-closure}(\{q_0\})\end{aligned}$$

$$\boxed{\delta(\{q_0, q_1, q_2\}, b) = \{q_0, q_1, q_2\}}$$

iii) find transition for New State  $\{q_1, q_2\}$

$$\begin{aligned}\delta(\{q_1, q_2\}, a) &= \epsilon\text{-closure}(\{q_1, q_2\}, a) \\&= \epsilon\text{-closure}(\{q_1, a\} \cup \{q_2, a\}) \\&= \epsilon\text{-closure}(\{q_1\} \cup \{q_1\}) \\&= \epsilon\text{-closure}(\{q_1\})\end{aligned}$$

$$\boxed{\delta(\{q_1, q_2\}, a) = \{q_1, q_2\}}$$

$$\epsilon\text{-closure } \{q_0\} = \overbrace{\{q_0, q_1, q_2\}}$$

$$\epsilon\text{-closure } \{q_1\} = \{q_1, q_2\}$$

$$\epsilon\text{-closure } \{q_2\} = \{q_2\}$$

iv)  $\delta(\{q_1, q_2\}, b) = \epsilon\text{-closure}(\{q_1, q_2\}, b)$

$$= \epsilon\text{-closure}(\{q_1, b\} \cup \{q_2, b\})$$

$$= \epsilon\text{-closure}(\phi \cup \{q_0\})$$

$$= \epsilon\text{-closure}(\{q_0\})$$

$$\boxed{\delta(\{q_1, q_2\}, b) = \{q_0, q_1, q_2\}}$$

STEP 4 Hence, the generated DFA is

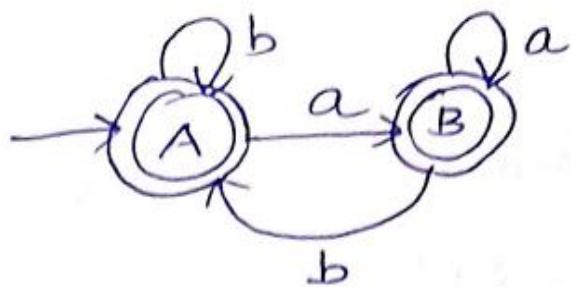
STATES / INPUT	a	b
* $(\{q_0, q_1, q_2\})$	$\{q_1, q_2\}$	$\{q_0, q_1, q_2\}$
* $(\{q_1, q_2\})$	$\{q_1, q_2\}$	$\{q_0, q_1, q_2\}$

States / Inputs	a	b
* A	B	A
* B	B	A

Assume  $\{q_0, q_1, q_2\}$  as A

$\{q_1, q_2\}$  as B

STEP 5 Draw Transition diagram for DFA.  
Mark start state as well as final state



Final states are  $(\{A\}, \{B\})$ .

# Thank You